

# Oracle inequality for the Lasso

$$Y = X\beta^0 + \varepsilon, \quad p \gg n$$

for the Lasso:

*Theorem 6.1 in Bühlmann and van de Geer (2011)*

assume: compatibility condition holds with compatibility constant  $\phi_0^2$  ( $\geq L > 0$ )

Then, on  $\mathcal{T}$  and for  $\lambda \geq 2\lambda_0$ :

$$\|X(\hat{\beta} - \beta^0)\|_2^2/n + \lambda\|\hat{\beta} - \beta^0\|_1 \leq 4\lambda^2 s_0 / \phi_0^2$$

recall:  $\mathcal{T} = \{2 \max_{j=1, \dots, p} |\varepsilon^T X^{(j)}|/n \leq \lambda_0\}$

$$\mathbb{P}[\mathcal{T}] \text{ large if } \lambda_0 \asymp \sqrt{\log(p)/n}$$

When does the compatibility condition hold?

*Corollary 6.8 from Bühlmann and van de Geer (2011) – modified form*

Assume that the row vectors of  $X$  are i.i.d. sampled from a sub-Gaussian distribution with mean zero and covariance matrix  $\Sigma$ . Assume that

- ▶  $\lambda_{\min}^2(\Sigma) > 0$
- ▶  $s_0 = |S_0| = O(\sqrt{n/\log(p)})$

Then, for some  $C > 0$ :

$$\phi_0^2 \geq C\lambda_{\min}^2(\Sigma) > 0 \text{ with probability } \rightarrow 1 \text{ (} n \rightarrow \infty \text{)}$$

**Example:** Toeplitz matrix  $\Sigma_{ij} = \rho^{|i-j|}$  ( $0 \leq \rho < 1$ ):  
 $\lambda_{\min}^2(\Sigma) \geq L_\rho > 0$  where  $L_\rho$  is independent of  $p$

## Implications of oracle inequality

assume that  $\phi_0^2 \geq L > 0$

$$\text{on } \mathcal{T}: \|X(\hat{\beta} - \beta^0)\|_2^2/n + \lambda\|\hat{\beta} - \beta^0\|_1 \leq 4\lambda^2 s_0/\phi_0^2$$

if  $\lambda(= 2\lambda_0) \asymp \sqrt{\log/p/n}$ : as  $p \geq n \rightarrow \infty$ ,

$$\|X(\hat{\beta} - \beta^0)\|_2^2/n = O_P(s_0 \log(p)/n)$$

$$\|\hat{\beta} - \beta^0\|_1 = O_P(s_0 \sqrt{\log(p)/n})$$

thus, when compatibility condition holds:

### 1. fast rate of convergence for prediction

if  $S_0$  with  $s_0 = o(n)$  would be known:

$$\|X\hat{\beta}_{\text{OLS}} - \beta^0\|_2^2/n = O_P(s_0/n)$$

$\rightsquigarrow$  factor  $\log(p)$  is the (small!) price for not knowing  $S_0$

### 2. estimation error for $\beta^0$ in terms of the $\ell_1$ -norm

# Variable screening

active set (of variables):  $S_0 = \{j; \beta_j^0 \neq 0\}$

estimated active set:  $\hat{S}_0 = \{j; \hat{\beta}_j \neq 0\}$

make an assumption that true regression coefficients are not too small

**"beta-min condition"** :  $\min_{j \in S_0} |\beta_j^0| > \underbrace{4\lambda s_0 / \phi_0^2}_{\text{bound for } \|\hat{\beta} - \beta^0\|_1}$

$\implies \mathbb{P}[\hat{S} \supseteq S_0] \geq \mathbb{P}[\mathcal{T}] = \text{"large"}$

with high probab: Lasso selects a superset of the active set  $S_0$

$\rightsquigarrow$  Lasso does not miss an important active variable!

$$\mathbb{P}[\hat{S} \supseteq S_0] \geq \mathbb{P}[\mathcal{T}] = \text{“large”}$$

Proof:

Suppose that  $\hat{S} \not\supseteq S_0$ :  $\leadsto$  there exists  $j^* \in S_0$  with  $\hat{\beta}_{j^*} = 0$

But then, on  $\mathcal{T}$ :

$$\|\hat{\beta} - \beta^0\|_1 \geq \|\hat{\beta}_{j^*} - \beta_{j^*}^0\| = |\beta_{j^*}^0| > 4\lambda s_0 / \phi_0^2$$

which is a contradiction to the oracle inequality

$$(\text{for } \|\hat{\beta} - \beta^0\|_1 \leq \lambda 4s_0 / \phi_0^2)$$

□

## Theory versus Practice

theory:

$$\mathbb{P}[\hat{S} \supseteq S_0] \rightarrow 1$$

if the following hold:

- ▶ compatibility condition for the (fixed) design  $X$
- ▶ beta-min condition
- ▶ i.i.d. Gaussian errors (can be relaxed)

in addition:  $|\hat{S}| \leq \min(n, p)$

hence: **huge dimensionality reduction if  $p \gg n$**

in practice:  $\mathbb{P}[\hat{S} \supseteq S_0]$  may not be so large...  
even if one chooses  $\lambda$  very small which results in a typically larger set  $\hat{S}$ ...

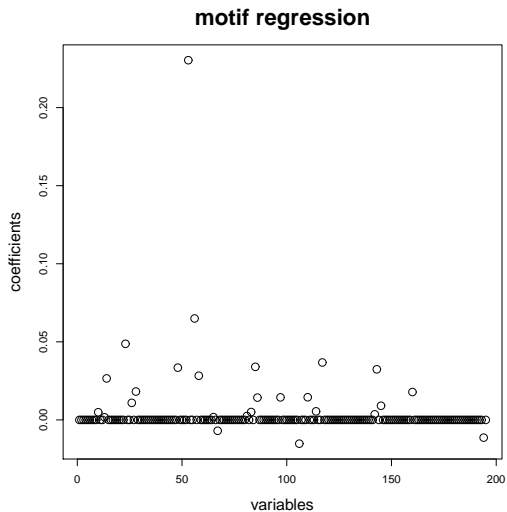
possible reasons to explain with theory:

- ▶ compatibility constant  $\phi_0^2$  might be very small (due to highly correlated columns in  $X$  or near linear dependence among a few columns of  $X$ )  
 $\leadsto \|\hat{\beta} - \beta^0\|_1 \leq 4\lambda s_0 / \phi_0^2$   
 $\leadsto$  requires a stronger beta-min condition!
- ▶ errors are non-Gaussian (heavy tailed)

it is “empirically evident” though:  $\mathbb{P}[\hat{S} \supseteq S_{\text{substantial}(C)}]$  large

where  $S_{\text{substantial}(C)} = \{j; |\beta_j^0| \geq \underbrace{C}_{\text{large}}\}$

## The Lasso workhorse



$$p = 195, n = 143, |\hat{S}(\lambda_{CV})| = 26$$



# Variable selection

under more restrictive **irrepresentable condition** or **neighborhood stability condition** on the design  $X$   
and assuming beta-min condition  $\min_{j \in S_0} |\beta_j^0| \gg \sqrt{s_0 \log(p)/n}$ :

$$\mathbb{P}[\hat{S} = S_0] \rightarrow 1 \quad (n \rightarrow \infty)$$

the irrepresentable condition is sufficient and essentially necessary for consistent variable selection

this condition is often not fulfilled in practice  
(and choosing the correct  $\lambda$  would be difficult as well)

↪ variable screening is realistic (“choose  $\lambda$  by CV”)  
variable selection is not very realistic

better “translation”:

LASSO = Least Absolute Shrinkage and **Screening** Operator

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better “translation”:

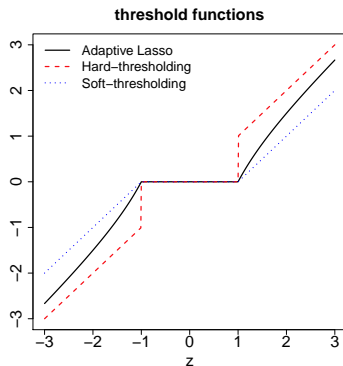
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version of Table 2.2 in the book:

property	design condition	size of non-zero coeff.
slow prediction conv. rate	no requirement	no requirement
fast prediction conv. rate	compatibility	no requirement
estimation error bound $\ \hat{\beta} - \beta^0\ _1$	compatibility	no requirement
variable screening	compatibility or restricted eigenvalue	beta-min condition weaker beta-min cond.
variable selection	neighborhood stability $\Leftrightarrow$ irrepresentable cond.	beta-min condition

# Adaptive Lasso

is a good way to address the bias problems of the Lasso  
for orthonormal design



two-stage procedure:

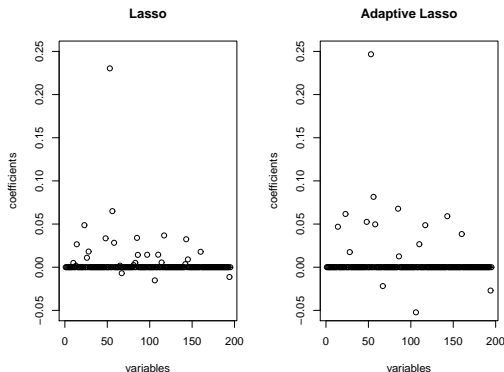
- ▶ initial estimator  $\hat{\beta}_{\text{init}}$ , e.g., the Lasso
- ▶ re-weighted  $\ell_1$ -penalty

$$\hat{\beta}_{\text{adapt}}(\lambda) = \operatorname{argmin}_{\beta} \left( \|Y - X\beta\|_2^2/n + \lambda \sum_{j=1}^p \frac{|\beta_j|}{|\hat{\beta}_{\text{init},j}|} \right)$$

adaptive Lasso often works well in practice (more sparse than Lasso) and has better theoretical properties than Lasso for variable screening (and selection) if the truth is assumed to be sparse

alternatives: thresholding the Lasso; Relaxed Lasso

# The adaptive Lasso workhorse



$$p = 195, n = 143, |\hat{S}_{\text{ada-Lasso}}(\lambda_{CV})| = 16$$

we will discuss later in the course the issue of assigning  
“significance of selected variables”

should we always use the adaptive Lasso?

- ▶ it's slightly more complicated – need two Lasso fits
- ▶ the differences in large-scale data are perhaps not so large
- ▶ I tend to say:  
“Yes, often the adaptive Lasso is perhaps a bit better”

# Computational algorithm for Lasso

can use a very generic coordinate descent algorithm (not gradient descent)

motivation of the algorithm:

consider the objective function and the corresponding Karush-Kuhn-Tucker (KKT) conditions by taking the sub-differential:

$$\begin{aligned} & \frac{\partial}{\partial j} (\|Y - X\beta\|_2^2/n + \lambda\|\beta\|_1) \\ = & G_j(\beta) + \lambda e_j, \\ & G(\beta) = -2X^T(Y - X\beta)/n, \\ & e_j = \text{sign}(\beta_j) \text{ if } \beta_j \neq 0, \quad e_j \in [-1, 1] \text{ if } \beta_j = 0 \end{aligned}$$



this implies (by setting the sub-differential to zero) the KKT-conditions (Lemma 2.1, Bühlmann and van de Geer (2011)):

$$\begin{aligned} G_j(\hat{\beta}) &= -\text{sign}(\hat{\beta}_j)\lambda \text{ if } \hat{\beta}_j \neq 0, \\ |G_j(\hat{\beta})| &\leq \lambda \text{ if } \hat{\beta}_j = 0. \end{aligned}$$

an interesting characterization of the Lasso solution!

in abbreviated form:

1: Let  $\beta^{[0]} \in \mathbb{R}^p$  be an initial parameter vector. For  $m = 1, 2, \dots$

2: **repeat**

3: Proceed componentwise  $j = 1, 2, \dots, p, 1, 2, \dots, p, 1, 2, \dots$   
update:

if  $|G_j(\underbrace{\beta_{-j}^{[m-1]}}_{\text{prev. parameter with } j\text{th comp}=0})| \leq \lambda$  : set  $\beta_j^{[m]} = 0$ ,

otherwise:  $\beta_j^{[m]}$  is the minimizer of the objective function with respect to the  $j$ th component but keeping all others fixed

4: **until** numerical convergence

- 1: Let  $\beta^{[0]} \in \mathbb{R}^p$  be an initial parameter vector. Set  $m = 0$ .
- 2: **repeat**
- 3: Increase  $m$  by one:  $m \leftarrow m + 1$ .  
Denote by  $\mathcal{S}^{[m]}$  the index cycling through the coordinates  $\{1, \dots, p\}$ :  
 $\mathcal{S}^{[m]} = \mathcal{S}^{[m-1]} + 1 \bmod p$ . Abbreviate by  $j = \mathcal{S}^{[m]}$  the value of  $\mathcal{S}^{[m]}$ .
- 4: if  $|\mathbf{G}_j(\beta_{-j}^{[m-1]})| \leq \lambda$  : set  $\beta_j^{[m]} = 0$ ,  
otherwise:  $\beta_j^{[m]} = \operatorname{argmin}_{\beta_j} \mathbf{Q}_\lambda(\beta_{+j}^{[m-1]})$ ,  
where  $\beta_{-j}^{[m-1]}$  is the parameter vector where the  $j$ th component is set to zero and  $\beta_{+j}^{[m-1]}$  is the parameter vector which equals  $\beta^{[m-1]}$  except for the  $j$ th component where it is equal to  $\beta_j$  (i.e. the argument we minimize over).
- 5: **until** numerical convergence

for the squared error loss: the update in Step 4 is explicit (a soft-thresholding operation)

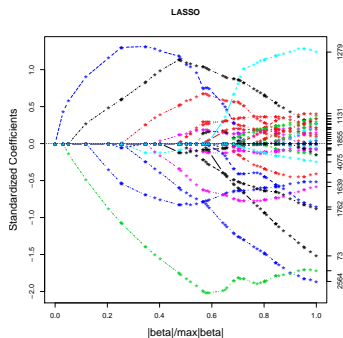
active set strategy can speed up the algorithm for sparse cases: mainly work on the non-zero coordinates and up-date all coordinates e.g. every 20th times

R-package `glmnet`

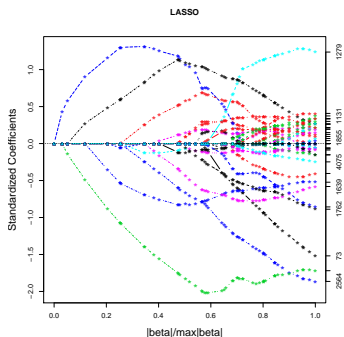
## The Lasso regularization path

compute  $\hat{\beta}(\lambda)$  over “all”  $\lambda$

- ▶ just a grid of  $\lambda$ -values and interpolate linearly (the true solution path over all  $\lambda$  is piecewise linear)
- ▶ for  $\lambda_{\max} = |2X^T Y/n|$ :  $\hat{\beta}(\lambda_{\max}) = 0$   
(because of KKT conditions!)



plot against  $\|\hat{\beta}(\lambda)\|_1 / \max_{\lambda} \|\hat{\beta}(\lambda)\|_1$  ( $\lambda$  small is to the right)



regularization path: in general, “not monotone in the non-zeros”  
 it can happen in general that e.g.

$$\hat{\beta}_j(\lambda) \neq 0, \hat{\beta}_j(\lambda') = 0 \text{ for } \lambda' < \lambda$$