

# Package ‘camtrapdp’

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**Title** Read and Manipulate Camera Trap Data Packages

**Version** 0.2.1

**Description** Read and manipulate Camera Trap Data Packages ('Camtrap DP').  
'Camtrap DP' (<<https://camtrap-dp.tdwg.org>>) is a data exchange format for camera trap data. With 'camtrapdp' you can read, filter and transform data (including to Darwin Core) before further analysis in e.g. 'camtraptor' or 'camtrapR'.

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**URL** <https://github.com/inbo/camtrapdp>,  
<https://inbo.github.io/camtrapdp/>

**BugReports** <https://github.com/inbo/camtrapdp/issues>

**Imports** cli, dplyr, frictionless (>= 1.1.0), memoise, purrr, readr

**Suggests** lubridate, testthat (>= 3.0.0), xml2

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|                 |  |
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| check_camtrapdp | <i>Check a Camera Trap Data Package object</i> |
|-----------------|--|

---

### Description

Checks if an object is a Camera Trap Data Package object with the required properties.

### Usage

```
check_camtrapdp(x)
```

### Arguments

x Camera Trap Data Package object, as returned by read\_camtrapdp().

### Value

x invisibly or error.

### Examples

```
x <- example_dataset()
check_camtrapdp(x) # Invisible return of x if valid
```

---

|             |                               |
|-------------|-------------------------------|
| deployments | <i>Get or set deployments</i> |
|-------------|-------------------------------|

---

**Description**

`deployments()` gets the deployments from a Camera Trap Data Package object. `deployments<-()` is the assignment equivalent. It should only be used within other functions, where the expected data structure can be guaranteed.

**Usage**

```
deployments(x)

deployments(x) <- value
```

**Arguments**

|                    |   |
|--------------------|---|
| <code>x</code>     | Camera Trap Data Package object, as returned by <code>read_camtrapdp()</code> . |
| <code>value</code> | A data frame to assign as deployments.  |

**Value**

`tibble()` data frame with deployments.

**See Also**

Other accessor functions: `events()`, `locations()`, `media()`, `observations()`, `taxa()`

**Examples**

```
x <- example_dataset()
# Get deployments
deployments(x)

# Set deployments (not recommended outside a function)
deployments(x) <- head(deployments(x), 1)
```

---

|        |                   |
|--------|-------------------|
| events | <i>Get events</i> |
|--------|-------------------|

---

**Description**

Gets the (unique) events from the observations of a Camera Trap Data Package object. Only observations with `observationLevel == "event"` are considered.

**Usage**

```
events(x)
```

**Arguments**

x Camera Trap Data Package object, as returned by `read_camtrapdp()`.

**Value**

`tibble()` data frame with the events, containing the following columns:

- deploymentID
- eventID
- eventStart
- eventEnd

**See Also**

Other accessor functions: `deployments()`, `locations()`, `media()`, `observations()`, `taxa()`

**Examples**

```
x <- example_dataset()
events(x)
```

---

example\_dataset

*Read the Camtrap DP example dataset*

---

**Description**

Reads the **Camtrap DP example dataset**. This dataset is maintained and versioned with the Camtrap DP standard.

**Usage**

```
example_dataset()
```

**Value**

Camera Trap Data Package object.

**Examples**

```
example_dataset()
```

---

filter\_deployments      *Filter deployments*

---

### Description

Subsets deployments in a Camera Trap Data Package object, retaining all rows that satisfy the conditions.

### Usage

```
filter_deployments(x, ...)
```

### Arguments

x                      Camera Trap Data Package object, as returned by read\_camtrapdp().  
...                     Filtering conditions, see dplyr::filter().

### Details

- Media are filtered on associated deploymentID.
- Observations are filtered on associated deploymentID.

### Value

x filtered.

### See Also

Other filter functions: [filter\\_media\(\)](#), [filter\\_observations\(\)](#)

### Examples

```
x <- example_dataset()

# Filtering returns x, so pipe with deployments() to see the result
x %>%
  filter_deployments(deploymentID == "62c200a9") %>%
  deployments()

# Filtering on deployments also affects associated media and observations
x_filtered <- filter_deployments(x, deploymentID == "62c200a9")
media(x_filtered)
observations(x_filtered)

# Filtering on multiple conditions (combined with &)
x %>%
  filter_deployments(latitude > 51.0, longitude > 5.0) %>%
  deployments()
```

```
# Filtering on dates is easiest with lubridate
library(lubridate, warn.conflicts = FALSE)
x %>%
  filter_deployments(
    deploymentStart >= lubridate::as_date("2020-06-19"),
    deploymentEnd <= lubridate::as_date("2020-08-30")
  ) %>%
  deployments()
```

---

 filter\_media

*Filter media*


---

## Description

Subsets media in a Camera Trap Data Package object, retaining all rows that satisfy the conditions.

## Usage

```
filter_media(x, ...)
```

## Arguments

`x` Camera Trap Data Package object, as returned by `read_camtrapdp()`.  
`...` Filtering conditions, see `dplyr::filter()`.

## Details

- Deployments are not filtered.
- Observations are filtered on associated `mediaID` (for media-based observations) and `eventID` (for event-based observations).

## Value

`x` filtered.

## See Also

Other filter functions: [filter\\_deployments\(\)](#), [filter\\_observations\(\)](#)

## Examples

```
x <- example_dataset()

# Filtering returns x, so pipe with media() to see the result
x %>%
  filter_media(captureMethod == "timeLapse") %>%
  media()

# Filtering on media also affects associated observations, but not deployments
```

```
x_filtered <- filter_media(x, favorite == TRUE)
observations(x_filtered)

# Filtering on multiple conditions (combined with &)
x %>%
  filter_media(captureMethod == "activityDetection", filePublic == FALSE) %>%
  media()

# Filtering on datetimes is easiest with lubridate
library(lubridate, warn.conflicts = FALSE)
x %>%
  filter_media(
    timestamp >= lubridate::as_datetime("2020-08-02 05:01:00"),
    timestamp <= lubridate::as_datetime("2020-08-02 05:02:00")
  ) %>%
  media()
```

---

filter\_observations     *Filter observations*

---

## Description

Subsets observations in a Camera Trap Data Package object, retaining all rows that satisfy the conditions.

## Usage

```
filter_observations(x, ...)
```

## Arguments

|     |   |
|-----|---|
| x   | Camera Trap Data Package object, as returned by <code>read_camtrapdp()</code> . |
| ... | Filtering conditions, see <code>dplyr::filter()</code> .                        |

## Details

- Deployments are not filtered.
- Media are filtered on associated `mediaID` (for media-based observations) and `eventID` (for event-based observations). Filter on `observationLevel == "media"` to only retain directly linked media.

## Value

x filtered.

## See Also

Other filter functions: [filter\\_deployments\(\)](#), [filter\\_media\(\)](#)

**Examples**

```
x <- example_dataset()

# Filtering returns x, so pipe with observations() to see the result
x %>%
  filter_observations(observationType == "animal") %>%
  observations()

# Filtering on observations also affects associated media, but not deployments
x %>%
  filter_observations(scientificName == "Vulpes vulpes", observationLevel == "event") %>%
  media()
x %>%
  filter_observations(scientificName == "Vulpes vulpes", observationLevel == "media") %>%
  media()

# Filtering on multiple conditions (combined with &)
x %>%
  filter_observations(
    deploymentID == "577b543a",
    scientificName %in% c("Martes foina", "Mustela putorius")
  ) %>%
  observations()

# Filtering on datetimes is easiest with lubridate
library(lubridate, warn.conflicts = FALSE)
x %>%
  filter_observations(
    eventStart >= lubridate::as_datetime("2020-06-19 22:00:00"),
    eventEnd <= lubridate::as_datetime("2020-06-19 22:10:00")
  ) %>%
  observations()
```

---

locations

*Get locations*


---

**Description**

Gets the (unique) locations from the deployments of a Camera Trap Data Package object.

**Usage**

```
locations(x)
```

**Arguments**

x Camera Trap Data Package object, as returned by `read_camtrapdp()`.



**Value**

`tibble()` data frame with the locations, containing the following columns:

- locationID
- locationName
- latitude
- longitude
- coordinateUncertainty

**See Also**

Other accessor functions: `deployments()`, `events()`, `media()`, `observations()`, `taxa()`

**Examples**

```
x <- example_dataset()
locations(x)
```

---

media

*Get or set media*

---

**Description**

`media()` gets the media from a Camera Trap Data Package object.  
`media<-()` is the assignment equivalent. It should only be used within other functions, where the expected data structure can be guaranteed.

**Usage**

```
media(x)
```

```
media(x) <- value
```

**Arguments**

`x` Camera Trap Data Package object, as returned by `read_camtrapdp()`.  
`value` A data frame to assign as media.

**Value**

`tibble()` data frame with media.

**See Also**

Other accessor functions: `deployments()`, `events()`, `locations()`, `observations()`, `taxa()`

### Examples

```
x <- example_dataset()
# Get media
media(x)

# Set media (not recommended outside a function)
media(x) <- head(media(x), 1)
```

---

observations

*Get observations*

---

### Description

`observations()` gets the observations from a Camera Trap Data Package object. `observations<-()` is the assignment equivalent. It should only be used within other functions, where the expected data structure can be guaranteed.

### Usage

```
observations(x)

observations(x) <- value
```

### Arguments

`x` Camera Trap Data Package object, as returned by `read_camtrapdp()`.  
`value` A data frame to assign as observations.

### Value

`tibble()` data frame with observations.

### See Also

Other accessor functions: [deployments\(\)](#), [events\(\)](#), [locations\(\)](#), [media\(\)](#), [taxa\(\)](#)

### Examples

```
x <- example_dataset()
# Get the observations
observations(x)

# Set observations (not recommended outside a function)
observations(x) <- head(observations(x), 1)
```

---

|                |  |
|----------------|--|
| read_camtrapdp | <i>Read a Camera Trap Data Package</i> |
|----------------|--|

---

### Description

Reads files from a **Camera Trap Data Package (Camtrap DP)** into memory.

### Usage

```
read_camtrapdp(file)
```

### Arguments

file                    Path or URL to a datapackage.json file.

### Value

Camera Trap Data Package object.

### Assign taxonomic information

Camtrap DP metadata has a taxonomic property that can contain extra information for each scientificName found in observations. Such information can include higher taxonomy (family, order, etc.) and vernacular names in multiple languages.

This function **will automatically include this taxonomic information in observations**, as extra columns starting with taxon..

### Assign eventIDs

Observations can contain two classifications at two levels:

**Media-based** observations (observationLevel = "media") are based on a single media file and are directly linked to it via mediaID.

**Event-based** observations (observationLevel = "event") are based on an event, defined as a combination of eventID, eventStart and eventEnd. This event can consist of one or more media files, but is not directly linked to these.

This function **will automatically assign eventIDs to media**, using media.deploymentID = event.deploymentID and eventStart <= media.timestamp <= eventEnd. Note that this can result in media being linked to multiple events (and thus being duplicated), for example when events and sub-events were defined.

### Examples

```
file <- "https://raw.githubusercontent.com/tdwg/camtrap-dp/1.0/example/datapackage.json"
x <- read_camtrapdp(file)
x
```

---

|      |                 |
|------|-----------------|
| taxa | <i>Get taxa</i> |
|------|-----------------|

---

**Description**

Gets the (unique) scientific names and associated taxonomic information from the observations of a Camera Trap Data Package object.

**Usage**

```
taxa(x)
```

**Arguments**

x Camera Trap Data Package object, as returned by `read_camtrapdp()`.

**Value**

`tibble()` data frame with the taxonomic information, containing at least a `scientificName` column.

**See Also**

Other accessor functions: `deployments()`, `events()`, `locations()`, `media()`, `observations()`

**Examples**

```
x <- example_dataset()
taxa(x)
```

---

|         |                               |
|---------|-------------------------------|
| version | <i>Get Camtrap DP version</i> |
|---------|-------------------------------|

---

**Description**

Extracts the version number used by a Camera Trap Data Package object. This version number indicates what version of the **Camtrap DP standard** was used.

**Usage**

```
version(x)
```

**Arguments**

x Camera Trap Data Package object, as returned by `read_camtrapdp()`. Also works on a Frictionless Data Package, as returned by `frictionless::read_package()`.

## Details

The version number is derived as follows:

1. The `version` attribute, if defined.
2. A version number contained in `x$profile`, which is expected to contain the URL to the used Camtrap DP standard.
3. `x$profile` in its entirety (can be `NULL`).

## Value

Camtrap DP version number (e.g. `1.0`).

## Examples

```
x <- example_dataset()
version(x)
```

---

write\_dwc

*Transform a Camera Trap Data Package to a Darwin Core Archive*

---

## Description

Transforms a Camera Trap Data Package object to a [Darwin Core Archive](#).

## Usage

```
write_dwc(x, directory)
```

## Arguments

`x` Camera Trap Data Package object, as returned by `read_camtrapdp()`.  
`directory` Path to local directory to write files to.

## Value

CSV and `meta.xml` files written to disk. And invisibly, a list of data frames with the transformed data.

## Transformation details

This function **follows recommendations** in Reyserhove et al. (2023) [doi:10.35035/doc0qzp2x37](https://doi.org/10.35035/doc0qzp2x37) and transform data to:

- An [Occurrence core](#).
- An [Audubon/Audiovisual Media Description extension](#).
- A `meta.xml` file.

Key features of the Darwin Core transformation:

- The Occurrence core contains one row per observation (`dwc:occurrenceID = observationID`).
- Only observations with `observationType = "animal"` and `observationLevel = "event"` are included, thus excluding observations that are (of) humans, vehicles, blanks, unknowns, unclassified and media-based.
- Deployment information is included in the Occurrence core, such as location, habitat, `dwc:samplingProtocol`, deployment duration in `dwc:samplingEffort` and `dwc:parentEventID = deploymentID` as grouping identifier.
- Event information is included in the Occurrence core, as event duration in `dwc:eventDate` and `dwc:eventID = eventID` as grouping identifier.
- Media files are included in the Audubon/Audiovisual Media Description extension, with a foreign key to the observation. A media file that is used for more than one observation is repeated.
- Metadata is used to set the following record-level terms:
  - `dwc:datasetID = id`.
  - `dwc:datasetName = title`.
  - `dwc:collectionCode`: first source in sources.
  - `dcterms:license`: license (name) in licenses with scope data. The license (name) with scope media is used as `dcterms:rights` in the Audubon Media Description extension.
  - `dcterms:rightsHolder`: first contributor in contributors with role `rightsHolder`.
  - `dwc:dataGeneralizations`: set if `coordinatePrecision` is defined.

## Examples

```
x <- example_dataset()
write_dwc(x, directory = "my_directory")

# Clean up (don't do this if you want to keep your files)
unlink("my_directory", recursive = TRUE)
```

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