Multivariate Statistics

Principal Component Analysis (PCA)

09.12.2015

- Get familiar with the multivariate counterparts of the expectation and the variance.
- See how principal component analysis (PCA) can be used as a dimension reduction technique.

- In your introductory course you started with **univariate statistics**. You had a look at **one** random variable X at a time. E.g., X = "measurement of temperature".
- A random variable can be characterized by its expectation μ and the variance σ² (or standard deviation σ).

$$\mu = E[X], \quad \sigma^2 = \operatorname{Var}(X) = E[(X - \mu)^2].$$

- A model that is often used is the normal distribution: $X \sim \mathcal{N}(\mu, \sigma^2)$.
- The normal distribution is fully characterized by the expectation and the variance.

- The unknown parameters μ and σ can be estimated from data.
- Say we observe *n* (independent) realizations of our random variable *X*: *x*₁,..., *x_n*.
- You can think of measuring *n* times a certain quantity, e.g. temperature.
- Usual parameter estimates are

$$\widehat{\mu} = \overline{x} = \frac{1}{n} \sum_{i=1}^{n} x_i, \quad \widehat{\sigma}^2 = \widehat{\operatorname{Var}}(X) = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \overline{x})^2.$$

- Now we are going to have a look at the situation where we measure **multiple things** simultaneously.
- Hence, we have a multivariate random variable (vector) <u>X</u> having m components: <u>X</u> ∈ ℝ^m.
- You can think of measuring temperature at two different locations or measuring temperature and pressure at one location (m = 2).
- In that case

$$\underline{X} = \left[\begin{array}{c} X^{(1)} \\ X^{(2)} \end{array} \right],$$

where $X^{(1)}$ is temperature and $X^{(2)}$ is pressure.

• A possible data-set now consists of *n* **vectors** of dimension 2 (or *m* in the general case):

$$\underline{x}_1,\ldots,\underline{x}_n,$$

where $\underline{x}_i \in \mathbb{R}^2$ (or \mathbb{R}^m).

Remark

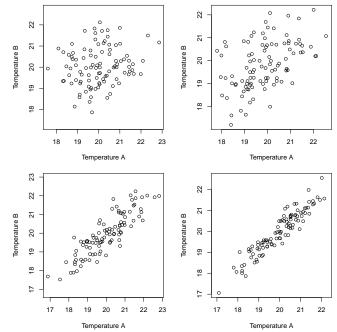
- In multiple linear regression we already had multiple variables per observation.
- There, we had one response variable and many predictor variables.
- Here, the situation is more general in the sense that we don't have a response variable but we want to model "relationships" between (any) variables.

- We need new concepts to model / describe this kind of data.
- We are therefore looking for the multivariate counterparts of the expectation and the variance.
- The (multivariate) **expectation** of <u>X</u> is defined as

$$E[\underline{X}] = \underline{\mu} = (\mu_1, \ldots, \mu_m)^T = (E[X^{(1)}], \ldots, E[X^{(m)}])^T.$$

• It's nothing else than the collection of the univariate expectations.

What about dependency?

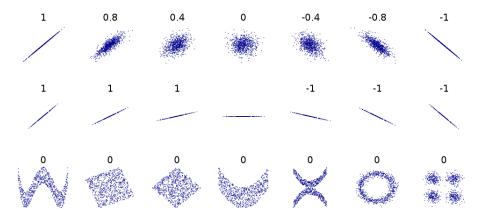


- We need a measure to characterize the dependency between the different components.
- The simplest thing one can think of is **linear dependency** between two components.
- The corresponding measure is the correlation ρ .
- ρ is dimensionless and it always holds that

 $-1 \leq \rho \leq 1$

- $|\rho|$ measures the **strength** of the linear relationship.
- The sign of ρ indicates the **direction** of the linear relationship.

Illustration: Empirical Correlation



Source: Wikipedia

- The formal definition of the correlation is based on the covariance.
- The covariance is an unstandardized version of the correlation. It is defined as

$$Cov(X^{(j)}, X^{(k)}) = E[(X^{(j)} - \mu_j)(X^{(k)} - \mu_k)].$$

• The correlation between $X^{(j)}$ and $X^{(k)}$ is then

$$\rho_{jk} = \text{Corr}(X^{(j)}, X^{(k)}) = \frac{\text{Cov}(X^{(j)}, X^{(k)})}{\sqrt{\text{Var}(X^{(j)}) \text{Var}(X^{(k)})}}$$

• You have seen the empirical version in the introductory course.

• The covariance matrix ${\bf \Sigma}$ is an $m \times m$ matrix with elements

$$\mathbf{X}_{jk} = \operatorname{Cov}(X^{(j)}, X^{(k)}) = E[(X^{(j)} - \mu_j)(X^{(k)} - \mu_k)].$$

- We also write $Var(\underline{X})$ or $Cov(\underline{X})$ instead of Σ .
- The special symbol $\pmb{\Sigma}$ is used in order to avoid confusion with the sum sign $\sum.$

• The covariance matrix contains a lot of information, e.g.

$$\mathbf{\Sigma}_{jj} = \mathsf{Var}(X^{(j)}).$$

This means that the diagonal consists of the individual variances.

• We can also compute the correlations via

$$\operatorname{Corr}(X^{(j)}, X^{(k)}) = \frac{\operatorname{Cov}(X^{(j)}, X^{(k)})}{\sqrt{\operatorname{Var}(X^{(j)})} \operatorname{Var}(X^{(k)})} = \frac{\mathbf{\Sigma}_{jk}}{\sqrt{\mathbf{\Sigma}_{jj} \mathbf{\Sigma}_{kk}}}$$

• Again, from a real data-set we can estimate these quantities with

$$\widehat{\underline{\mu}} = \left[\overline{x}^{(1)}, \overline{x}^{(2)}, \dots, \overline{x}^{(m)}\right]^T$$

$$\widehat{\mathbf{X}}_{jk} = \frac{1}{n-1} \sum_{i=1}^n (x_i^{(j)} - \widehat{\mu}_j) (x_i^{(k)} - \widehat{\mu}_k),$$

• Or more directly the whole matrix

$$\widehat{\mathbf{X}} = \frac{1}{n-1} \sum_{i=1}^{n} (\underline{x}_i - \underline{\widehat{\mu}}) (\underline{x}_i - \underline{\widehat{\mu}})^T.$$

• Remember: (Empirical) correlation only measures strength of **linear** relationship between two variables.

The following table illustrates how the expectation and the variance (covariance matrix) change when **linear transformations** are applied to the univariate random variable X or the multivariate random vector X.

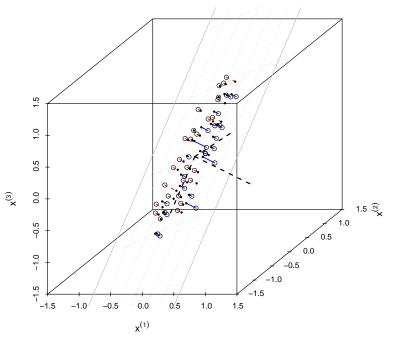
UnivariateMultivariateY = a + bX $\underline{Y} = \underline{a} + \underline{BX}$ E[Y] = a + bE[X] $E[\underline{Y}] = \underline{a} + \underline{BE[X]}$ $Var(Y) = b^2 Var(X)$ $Var(\underline{Y}) = \underline{BX}_X \underline{B}^T$

where $a, b \in \mathbb{R}$ and $\underline{a} \in \mathbb{R}^m, \mathbf{B} \in \mathbb{R}^{m \times m}$.

Goal: Dimensionality reduction.

- We have *m* different dimensions (variables) but we would like to find "a few specific dimensions (projections) of the data that contain most variation".
- If two specific dimensions of the data-set contain most variation, visualizations will be easy (plot these two!).
- Such a plot then can be used to check for any "structure".

Illustration of Artificial 3-Dim Data-Set



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- We have to be more precise with what we mean with "variation".
- We define the total variation in the data as the sum of all individual empirical variances

$$\sum_{j=1}^{m} \widehat{\operatorname{Var}}(X^{(j)}) = \sum_{j=1}^{m} \widehat{\sigma}^{2}(X^{(j)}).$$

- How can we now find projections that contain most variation?
- Conceptually, we are looking for a new coordinate system with basis vectors <u>b</u>₁,..., <u>b</u>_m ∈ ℝ^m.

• Of course, our data-points $\underline{x}_i \in \mathbb{R}^m$ will then have **new coordinates**

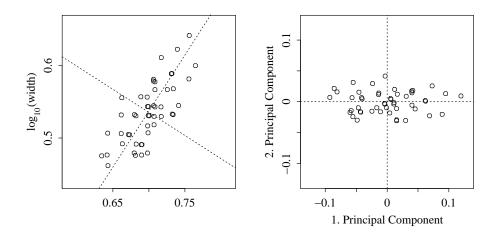
$$z_i^{(k)} = \underline{x}_i^T \underline{b}_k, \ k = 1, \dots, m$$

(= projection on new basis vectors).

- How should we choose the new basis?
 - ► The first basis vector <u>b</u>₁ should be chosen such that Var(Z⁽¹⁾) is maximal (i.e. it captures most variation).
 - The second basis vector \underline{b}_2 should be **orthogonal** to the first one $(\underline{b}_2^T \underline{b}_1 = 0)$ such that $\widehat{Var}(Z^{(2)})$ is **maximized**.
 - And so on...

- The new basis vectors are the so-called principal components.
- The individual components of these basis vectors are called **loadings**. The loadings tell us how to interpret the new coordinate system (i.e., how the old variables are weighted to get the new ones).
- The coordinates with respect to the new basis vectors (the transformed variable values) are the so-called **scores**.

PCA: Illustration in Two Dimensions



• We could find the first basis vector <u>b</u>₁ by solving the following maximization problem

$$\max_{\underline{b}:\|b\|=1}\widehat{\mathsf{Var}}(\mathbf{X}\underline{b}),$$

where \mathbf{X} is the matrix that has different observations in different rows and different variables in different columns (like the design matrix in regression).

- It can be shown that \underline{b}_1 is the (standardized) eigenvector of $\widehat{\mathbf{X}}_X$ that corresponds to the largest eigenvalue.
- Similarly for the other vectors $\underline{b}_2, \ldots, \underline{b}_m$.

• To summarize: We are performing a **transformation to new** variables

$$\underline{z}_i = \mathbf{B}^T (\underline{x}_i - \underline{\widehat{\mu}}),$$

where the transformation matrix **B** is orthogonal and contains the \underline{b}_k 's as columns.

- In general we also subtract the mean vector to ensure that all components have mean 0.
- **B** is the matrix of (standardized) eigenvectors corresponding to the eigenvalues λ_k of $\widehat{\mathbf{X}}_X$ (in decreasing order).

• Hence, we have

$$\widehat{\mathsf{Var}}(\underline{Z}) = \widehat{\mathbf{\Sigma}}_{Z} = \mathbf{B}^{T} \widehat{\mathbf{\Sigma}}_{X} \mathbf{B} = \begin{bmatrix} \lambda_{1} & 0 & \dots & 0 \\ 0 & \lambda_{2} & \dots & 0 \\ \vdots & \vdots & \ddots & \\ 0 & 0 & \dots & \lambda_{m} \end{bmatrix}$$

$$\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_m \geq 0.$$

- Hence, the variance of the different components of <u>Z</u> is given by the corresponding **eigenvalue** (values on the diagonal).
- Moreover, the different components are **uncorrelated** (because the off-diagonal elements of the covariance matrix of <u>Z</u> are all zero).

• The variance is **not** invariant under rescaling.

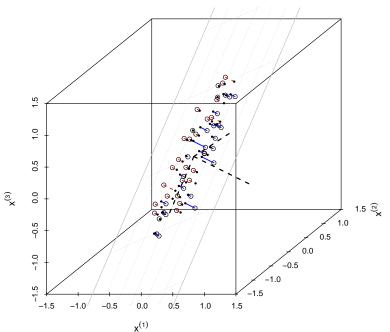
- If we change the units of a variable, that will change the variance (e.g. when measuring a length in [m] instead of [mm]).
- Therefore, if variables are measured on very different scales, they should first be **standardized** to comparable units.
- This can be done by standardizing each variable to variance 1.
- Otherwise, PCA can be misleading.

- At the beginning we were talking about dimensionality reduction.
- We can achieve this by simply looking at the first *p* < *m* principal components (and ignoring the remaining components).
- The **proportion** of the variance that is explained by the first *p* principal components is

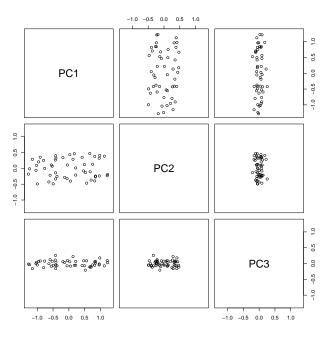
$$\frac{\sum_{j=1}^{p} \lambda_j}{\sum_{j=1}^{m} \lambda_j}.$$

- For visualization of our data, we can for example use a scatterplot of the first two principal components.
- It should show "most of the variation".

Illustration



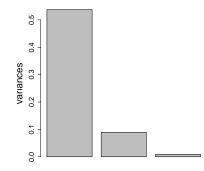
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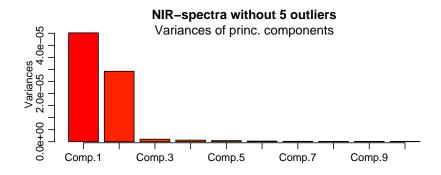
Loadings

	PC1	PC2	PC3
x1	-0.395118451	0.06887762	0.91604437
x2	-0.009993467	0.99680385	-0.07926044
xЗ	-0.918575822	-0.04047172	-0.39316727

Screeplot



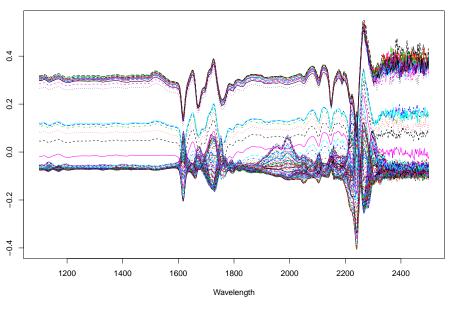
- Sometimes we see a sharp drop (after component *p*) when plotting the eigenvalues (in decreasing order).
- \rightarrow Consider only the first *p* components.



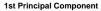
• This plot is also known as the scree-plot.

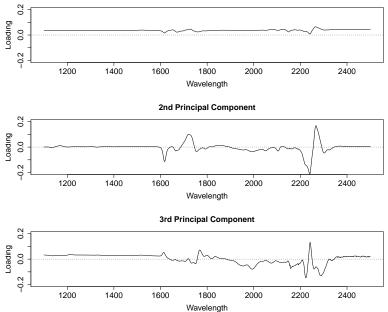
- An **NIR-spectrum** can be thought of as a multivariate observation (the different variables are the measurements at different wavelengths).
- A spectrum has the property that the different variables are "ordered" and we can plot one observation as a "function" (see plot on next slide).
- If we apply PCA to this kind of data, the individual components of the <u>b</u>_k's (the so called **loadings**) can again be plotted as spectra.
- As an example we have a look at spectra measured at different time-points of a chemical reaction.

Illustration: Spectra (centered at each wavelength)

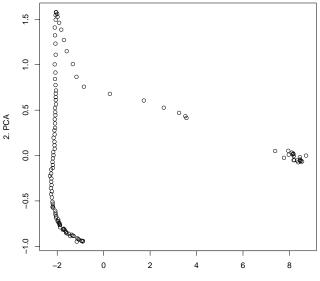


One observation is one spectrum, i.e. a whole "function".



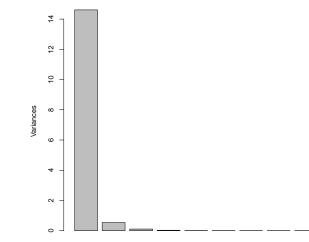


Scatterplot of the First Two Principal Components



1. PCA

Scree-Plot



If we restrict ourselves to the first p < m principal components we have

$$\underline{x}_i - \underline{\widehat{\mu}} = \underline{\widehat{x}}_i + \underline{e}_i$$

where

$$\underline{\widehat{x}}_i = \sum_{k=1}^p z_i^{(k)} \underline{\underline{b}}^{(k)}, \quad \underline{\underline{e}}_i = \sum_{k=p+1}^m z_i^{(k)} \underline{\underline{b}}^{(k)}.$$

Linear Algebra

It can be shown that the data matrix consisting of the \hat{x}_i is the **best** approximation of our original (centered) data matrix if we restrict ourselves to matrices of rank p (with respect to the Frobenius norm), i.e. it has smallest

$$\sum_{i,j} \left(e_i^{(j)} \right)^2.$$

Statistics

It's the best approximation in the sense that it has the smallest sum of variances

$$\sum_{j=1}^m \widehat{\operatorname{Var}}(E^{(j)}).$$

PCA via Singular Value Decomposition (SVD)

- We can also get the principal components from the singular value decomposition (SVD) of the data matrix **X**.
- For that reason we require **X** to have **centered columns**! $\frac{1}{2}$
- Why does this work?
 SVD of X yields the decomposition

 $\bm{X} = \bm{U}\bm{D}\bm{V}^{\mathcal{T}}$

where

- ► **U** is *n* × *n* and orthogonal
- ► D is n × m and generalized diagonal (containing the so-called singular values in descending order)
- **V** is $m \times m$ and orthogonal

Properties of SVD

- The (standardized) eigenvectors of $\mathbf{X}^T \mathbf{X}$ make up the columns of \mathbf{V} .
- The singular values are the square roots of the eigenvalues of $\mathbf{X}^T \mathbf{X}$.

But what is $\mathbf{X}^T \mathbf{X}$? If the columns of \mathbf{X} are **centered**, this is the rescaled (empirical) covariance matrix $\widehat{\mathbf{\Sigma}}_X$, because

$$(\mathbf{X}^{\mathsf{T}}\mathbf{X})_{jk} = \sum_{i=1}^{n} (\underline{x}_i \underline{x}_i^{\mathsf{T}})_{jk} = \sum_{i=1}^{n} x_i^{(j)} x_i^{(k)} = (n-1)\widehat{\mathbf{X}}_{jk}.$$

Hence, the singular value decomposition of the **centered** data-matrix automatically gives us the principal components (in V).

The data-matrix in new coordinates is given in **UD**.

- PCA is a useful tool for dimension reduction.
- New basis system is given by (standardized) eigenvectors of covariance matrix.
- Eigenvalues are the variances of the new coordinates.
- In the case of spectra, the loadings can again be plotted as spectra.